

Zero-Sum Repeated Games with Stage Duration and Public Signals

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1. Repeated games with public signals

A zero-sum repeated game with symmetric information, in which the signal depends only on the current state is a 7-tuple $(A, \Omega, f, I, J, g, q)$, where:

- A is the finite set of signals;
- Ω is the finite set of states;
- $f : \Omega \rightarrow A$ is a deterministic signaling function on Ω ;
- I (resp. J) is the finite set of actions of player 1 (resp. player 2);
- $g : I \times J \times \Omega \rightarrow \mathbb{R}$ is the payoff function of player 1;
- $q : I \times J \rightarrow \{\text{matrices } |\Omega| \times |\Omega| \text{ such that } q_{\omega_1\omega_2}(i, j) \geq 0 \text{ for } \omega_1 \neq \omega_2, q_{\omega\omega}(i, j) \in [-1, 0], \text{ and } \sum_{\omega_2 \in \Omega} q_{\omega_1\omega_2}(i, j) = 0\}$ is the kernel function.

The game is played in discrete time. An initial state $\omega_1 \in \Omega$ is chosen according to given probability law p_0 . At stage $n \in \mathbb{N}^*$:

1. The current state is $\omega_n \in \Omega$. Players do not observe it, but they observe the signal $\alpha_n = f(\omega_n)$;
2. Players choose their mixed actions, $x_n \in \Delta(I)$ and $y_n \in \Delta(J)$;
3. An action $i_n \in I$ (resp. $j_n \in J$) is chosen according to x_n (resp. y_n). Both actions are observed by both players;
4. The payoff is $g_n = g(i_n, j_n, \omega_n)$. The new state is ω_{n+1} with probability

$$\begin{cases} q_{\omega_n\omega_{n+1}}(i_n, j_n) & , \text{ if } \omega_{n+1} \neq \omega_n; \\ 1 + q_{\omega_n\omega_{n+1}}(i_n, j_n) & , \text{ if } \omega_{n+1} = \omega_n. \end{cases}$$

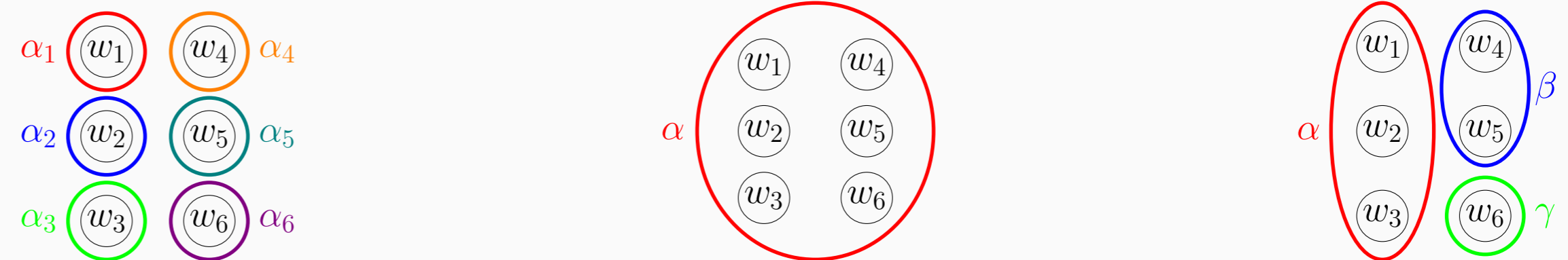
A strategy consists of choosing x_n and y_n at each stage (taking into account past actions and received signals).

If A is a singleton, then the game is a *state-blind repeated game*. If $A = \Omega$ and $f = Id$, then the game is a stochastic game, i.e. players can observe the state.

References

- [1] A. Neyman. Stochastic games with short-stage duration. *Dynamic Games and Applications*, 3(2):236–278, 2013.
- [2] S. Sorin and G. Vigeral. Operator approach to values of stochastic games with varying stage duration. *International Journal of Game Theory*, 45(1):389–410, 2016.
- [3] S. Sorin. Limit value of dynamic zero-sum games with vanishing stage duration. *Mathematics of Operations Research*, 43(1):51–63, 2017.
- [4] J. Renault and B. Ziliotto. Hidden stochastic games and limit equilibrium payoffs. *Games and Economic Behavior*, 124:122–139, 2020.
- [5] B. Ziliotto. Zero-sum repeated games: Counterexamples to the existence of the asymptotic value and the conjecture $\max\min = \lim v_n$. *The Annals of Probability*, 44(2):1107 – 1133, 2016.

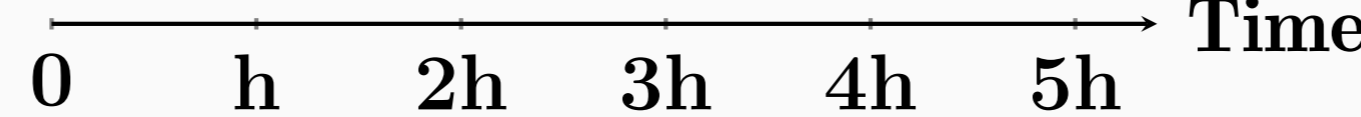
2. Examples of signalling on the states



- (a) Perfect observation of the state, i.e. there are 6 signals $\alpha_1, \dots, \alpha_6$; and $f(w_i) := \alpha_i$.
- (b) State-blind case. There is only one signal α , and $f(w_i) := \alpha$.
- (c) Intermediate case. $f(w_1) = f(w_2) = f(w_3) = \alpha$, $f(w_4) = f(w_5) = \beta$, $f(w_6) = \gamma$.

3. Stage duration

Fix a repeated game $G = (A, \Omega, f, I, J, g, q)$. Game with stage duration h is the repeated game $G_h = (A, \Omega, f, I, J, g^h, q^h)$, where $g^h = hg$ and $q^h = hq$, i.e. the kernel and the payoff function are proportional to stage duration h . We may think that the players act at times $0, h, 2h, \dots$, and not at times $0, 1, 2, \dots$, as in usual repeated game:



For each $\lambda > 0$ and small h , the λ -discounted payoff of the game G_h is (depending on the strategy profile (σ, τ) , and initial probability on the states p)

$$G_{\sigma, \tau}^p = E_{\sigma, \tau}^p \left(\lambda \sum_{i=1}^{\infty} (1 - \lambda h)^{i-1} g_i^h \right).$$

The value $v_{h, \lambda} : \Delta(\Omega) \rightarrow \mathbb{R}$ is defined by $v_{h, \lambda}(p) = \sup_{\sigma} \inf_{\tau} G_{\sigma, \tau}^p = \inf_{\tau} \sup_{\sigma} G_{\sigma, \tau}^p$.

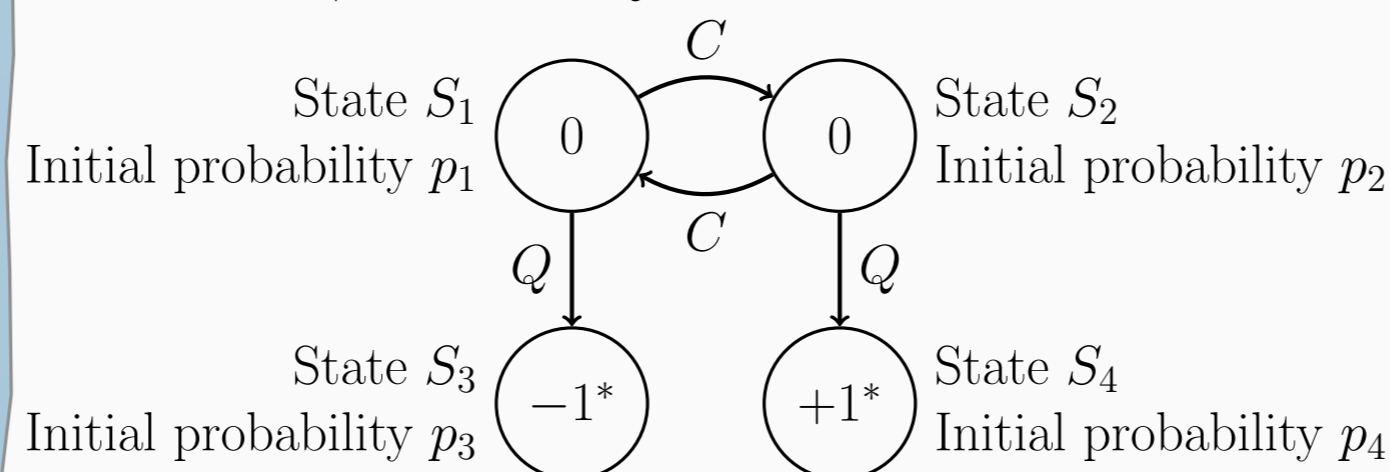
Stochastic games with stage duration were first introduced in [1].

Proposition 1 [1,2]: If players can observe the states (i.e. $f(\omega_i) = \alpha_i$), then:

1. $\lim_{h \rightarrow 0} v_{h, \lambda} = v_{1, \frac{\lambda}{1+\lambda}}$;
2. $\lim_{h \rightarrow 0} v_{h, \lambda}$ is a unique solution of $\lambda v(\omega) = \text{val}_{I \times J} [g(i, j, \omega) + \sum_{\omega' \in \Omega} q_{\omega\omega'}(i, j) \cdot v(\omega')]$;
3. The limits $\lim_{\lambda \rightarrow 0} \lim_{h \rightarrow 0} v_{h, \lambda}$ and $\lim_{\lambda \rightarrow 0} v_{1, \lambda}$ exist or do not exist simultaneously. In the case of existence, they are equal to each other.

4. An example

Consider a 1-player state-blind game with 2 actions, C and Q .



For this game, we have

$$\lim_{h \rightarrow 0} v_{h, \lambda}(p_1, p_2, p_3, p_4) = p_4 - p_3 + \frac{1}{1+\lambda} \max\{0, p_2 - p_1\};$$

$$v_{1, \lambda}(p_1, p_2, p_3, p_4) = p_4 - p_3 + p_2(1 - \lambda) + p_1(1 - \lambda)^2.$$

Note all of the assertions of Proposition 1 do not hold here.

5. First result

If X is finite, $\zeta \in \Delta(X)$, and μ is a $|X| \times |X|$ matrix, denote

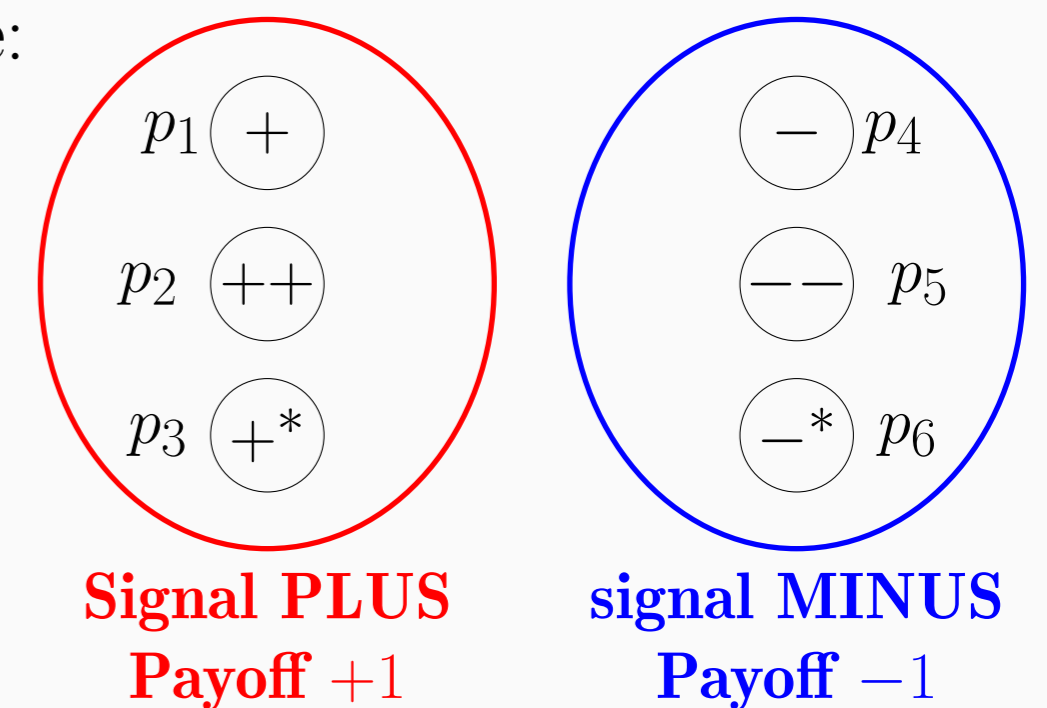
$$\zeta * \mu(x) := \sum_{x' \in X} \zeta(x') \cdot \mu_{x'x}.$$

Theorem 1: If $(A, \Omega, f, I, J, g, q)$ is a state-blind repeated game, then uniform limit $\lim_{h \rightarrow 0} v_{h, \lambda}(p)$ exists and is a unique viscosity solution of

$$\lambda v(p) = \text{val}_{I \times J} [g(i, j, p) + \langle (p * q(i, j))(\cdot), \nabla v(p) \rangle].$$

6. Second result

Consider a game from [4], similar to a game from [5]. It has 6 states, $+, ++, +^*, -, --, -^*$. The states $+^*$ and $-^*$ are absorbing. Payoff and signalling structure:



The actions of player 1 are T, M, B , and the actions of player 2 are L, M, R, Q . The transition probability matrices:

	L	M	R	Q
T	-	--	--	--
M	--	-	-	-
B	++	++	++	++

	L	M	R	Q
T	+	++	++	--
M	++	+	++	--
B	++	++	+	--

Figure 2: State $-$ Figure 3: State $+$

	L	M	R	Q
T	$\frac{1}{2}\{-\} + \frac{1}{2}\{--\}$	--	--	--
M	--	$\frac{1}{2}\{-\} + \frac{1}{2}\{--\}$	$\frac{1}{2}\{-\} + \frac{1}{2}\{--\}$	$\frac{1}{2}\{-\} + \frac{1}{2}\{--\}$
B	$-^*$	$-^*$	$-^*$	$-^*$

Figure 4: State $--$

	L	M	R	Q
T	$\frac{1}{3}\{++\} + \frac{2}{3}\{+\}$	++	++	$+^*$
M	++	$\frac{1}{3}\{++\} + \frac{2}{3}\{+\}$	++	$+^*$
B	++	++	$\frac{1}{3}\{++\} + \frac{2}{3}\{+\}$	$+^*$

Figure 5: State $++$

Theorem 2: Denote $p = (p_1, p_2, p_3, p_4, p_5, p_6)$. For the above game,

1. $\lim_{\lambda \rightarrow 0} v_{1, \lambda}(p)$ does not exist [4,5];
2. Uniform limit $\lim_{\lambda \rightarrow 0} \lim_{h \rightarrow 0} v_{h, \lambda}(p)$ exists, and it equals

$$\begin{cases} \frac{7}{11}p_1 - p_2 - p_3 + \frac{5}{11}p_4 - p_5 + p_6 & , \text{ if } \frac{p_2}{p_1+p_2} \leq \frac{2}{3} \text{ and } \frac{p_5}{p_4+p_5} \leq \frac{3}{4}; \\ \frac{7}{11}p_1 - p_2 - p_3 + \frac{7}{11}p_4 + \frac{7}{11}p_5 + p_6 & , \text{ if } \frac{p_2}{p_1+p_2} \leq \frac{2}{3} \text{ and } \frac{p_5}{p_4+p_5} > \frac{3}{4}; \\ -\frac{5}{11}p_1 - \frac{5}{11}p_2 - p_3 + \frac{5}{11}p_4 - p_5 + p_6 & , \text{ if } \frac{p_2}{p_1+p_2} > \frac{2}{3} \text{ and } \frac{p_5}{p_4+p_5} \leq \frac{3}{4}; \\ -\frac{5}{11}p_1 - \frac{5}{11}p_2 - p_3 + \frac{7}{11}p_4 + \frac{7}{11}p_5 + p_6 & , \text{ if } \frac{p_2}{p_1+p_2} > \frac{2}{3} \text{ and } \frac{p_5}{p_4+p_5} > \frac{3}{4}. \end{cases}$$

7. Final remarks

1. In case when players observe the state, the value of a continuous-time zero-sum Markov game (CTZSMG) coincides with the value of analogous stochastic game when its stage duration tends to 0. In the state-blind case, the same thing holds, if instead of a CTZSMG we consider its discretization, in which players can act only at times $0, h, 2h, \dots$, where h tends to 0. This implies that the general case with public signals may also be connected with CTZSMGs. The discretization of CTZSMGs is studied in [3].
2. Instead of assuming that each stage has duration h , one may assume that n -th stage duration is h_n , so that n -th stage payoff and kernel are $h_n g$ and $h_n q$ respectively. We are interested in the behavior of the value when $\sup\{h_n\} \rightarrow 0$. One can prove that Theorems 1 and 2 still hold in this more general framework.